

SUPERSYMMETRIC LOCALIZATIONS

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WHAT ARE LOCALIZATIONS?

Let's integrate an object α (a function, differential form, superfunction, path integrand ..) over some measure space M :

$$\int_M \alpha$$

That's complex; so let us split M into two pieces: $M = A \sqcup B$ where A is "bigger" than B .

$$\int_M \alpha = \int_A \alpha + \int_B \alpha = \int_B \alpha$$

If $\int_A \alpha = 0$ for some miraculous reason. We say that $\int_M \alpha$ is **localized** around B .

WHAT ARE SUPER SYMMETRIC LOCALIZATIONS?

The properties of super integration give us a new way of thinking about localizations!

Let $M = M^{(n|m)}$ be a supermanifold with dimension $(n|m)$. Let f be a function on M and Q a fermionic vectorfield such that:

$$Q(f) = 0$$

Further assume that we can find around a point $p \in M$ local coordinates (x^i, ψ^j) such that: $Q = \frac{\partial}{\partial \psi^1}$

$$\int d\psi^1 \dots d\psi^m f = \int d\psi^2 \dots d\psi^m \left(\frac{\partial}{\partial \psi^1} f \right) = 0$$

The integral over a neighbourhood of p does not contribute to the integral $\int_M f$!

This leads us to the conclusion:

$$\int_M f = \int_{M-N} f$$

With:

$$N = \left\{ p \in M \mid Q = \frac{\partial}{\partial \psi^1} \text{ in a neighbourhood of } p \right\}$$

This is a **supersymmetric localization**.

EQUIVARIANT DIFFERENTIAL FORMS

Let M be a compact manifold, G a compact Lie group with algebra \mathfrak{g} and an action $G \times M \mapsto M$ on M .

Let:

$$S(\mathfrak{g}^*) = \left\{ f : \mathfrak{g} \mapsto \mathbb{R} \mid f \text{ is a polynomial} \right\}$$

With " f is a polynomial" we mean that f is a polynomial over a basis $\{\alpha_1, \dots, \alpha_n\}$ of \mathfrak{g}^* for example:

$$f(\cdot) = 5\alpha_1(\cdot)^3 + \alpha_2(\cdot)\alpha_4(\cdot)$$

Let's now consider:

$$f \in S(\mathfrak{g}^*) \otimes \Omega^*(M, \mathbb{R})$$

f takes an element of \mathfrak{g} and returns an ordinary differential form:

$$f : \mathfrak{g} \mapsto \Omega^*(M, \mathbb{R})$$

We want a cohomology theory similar to deRahm's build on the forms $S(\mathfrak{g}^*) \otimes \Omega^*(M, \mathbb{R})$. Unfortunately, that does not work. To get a proper theory we need a subspace of $S(\mathfrak{g}^*) \otimes \Omega^*(M, \mathbb{R})$.

$g \in G$ can act on both sides of f :

$$f(\cdot) \mapsto f(Ad_g(\cdot))$$

$$f(\cdot) \mapsto g^* f(\cdot)$$

Where $Ad_g(h) = ghg^{-1}$ for $g \in G$ and $h \in \mathfrak{g}$. (For matrix groups.)

We need the subspace of *equivariant* f the **equivariant differential forms**:

$$\begin{aligned} (S(\mathfrak{g}^*) \otimes \Omega^*(M, \mathbb{R}))^G &= \left\{ f \in S(\mathfrak{g}^*) \otimes \Omega^*(M, \mathbb{R}) \mid g^* f(\cdot) = f(Ad_g(\cdot)) \forall g \in G \right\} \\ &= \Omega_G^*(M) \end{aligned}$$

This is the proper space to define the cohomology theory on. We need a nilpotent operator.

A nilpotent operator:

Observation: A $X \in \mathfrak{g}$ generates a vectorfield X_M on M via:

$$X_M(h)(p) = \left. \frac{d}{dt} \right|_{t=0} h(\exp(-tX)p)$$

For a $p \in M$ and a $h \in C^\infty(M, \mathbb{R})$.

Now define the nilpotent operator

$$D : (S(\mathfrak{g}^*) \otimes \Omega^*(M, \mathbb{R}))^G \mapsto (S(\mathfrak{g}^*) \otimes \Omega^*(M, \mathbb{R}))^G$$

by:

$$D(h \otimes \alpha)(X) = h(X) \otimes d\alpha + h(X) \otimes \iota_{X_M} \alpha$$

or:

$$D = d + \iota_{X_M}$$

This is nilpotent on $\Omega_G^*(M)$ because:

$$D^2 = d^2 + d\iota_{X_M} + \iota_{X_M}d + \iota_{X_M}^2 = 0 + \mathcal{L}_{X_M} + 0 = 0$$

Due to Cartan's magic formula.

The Lie derivative is not 0 for general forms but for $\alpha \in \Omega_G^*(M)$:

$$\mathcal{L}_{X_M}\alpha(X) = \lim_{t \rightarrow 0} \frac{(1 - tX)^*\alpha(X) - \alpha(X)}{t}$$

$$= \lim_{t \rightarrow 0} \frac{\alpha((1 - tX)X(1 + tX)) - \alpha(X)}{t} = \lim_{t \rightarrow 0} \frac{\alpha(X + t[X, X]) - \alpha(X)}{t} = 0$$

CARTAN MODEL OF EQUIVARIANT COHOMOLOGY

A form $f = h(\cdot) \otimes \alpha \in \Omega_G^*(M)$ with $h \in S(\mathfrak{g}^*)$ and $\alpha \in \Omega^*(M)$ has the **grading**:

$$\deg(f) = \deg(\alpha) + 2\deg(h)$$

$D = d + \iota_{X_M}$ increases the grading by 1.

Now we can define the **equivariant coboundarys** B_G^* and the **equivariant cocycles** Z_G^* :

$$Z_G^* = \text{kern}(D)$$

$$B_G^* = \text{Im}(D)$$

And finally the **equivariant cohomology**:

$$H_G^*(M) = \frac{Z_G^*}{B_G^*}$$

Final Remarks:

- ⊗ There are more models of equivariant cohomology like the **Weil** and **BRST** model.
- ⊗ The equivariant cohomology is usually defined in a more general way by the means of universal bundles. That is complex because the definition involves infinite dimensional manifolds.

For more details see [2] and [1]

THE ATIYAH BOTT LOCALIZATION:

Theorem:

Let G be a compact Lie group, \mathfrak{g} its algebra. M is an even dimensional compact manifold with dimension $\dim(M) = n = 2l$

The Atiyah Bott Localization formula:

$$\int_M \alpha(X)_{[n]} = (-2\pi)^l \sum_{p \in M_0(X)} \frac{\alpha(X)_{[0]}(p)}{e_F(X)(p)}$$

Where $X \in \mathfrak{g}$, α an equivariantly closed differential form, $M_0(X)$ the set of *isolated* zeros of X_M .

$e_F(X)(p)$ is the so called equivariant Euler class of the normal bundle of the point p .

Lemma: $\alpha(X)_{[n]}$ is d -exact outside $M_0(X)$.

We can find a form θ (with the use of a G invariant metric) such that $\iota_{X_M}\theta = 0$ and $D\theta$ is invertible on $M - M_0(X)$. Then we have on $M - M_0(X)$:

$$\alpha(X)_{[n]} = d\left(\frac{\theta \wedge \alpha(X)}{D\theta}\right)_{[n-1]}$$

because:

$$d\left(\frac{\theta \wedge \alpha(X)}{D\theta}\right)_{[n-1]} = D\left(\frac{\theta \wedge \alpha(X)}{D\theta}\right)_{[n-1]} = \left(\frac{D\theta}{D\theta}\alpha(X)\right)_{[n]} = \alpha(X)_{[n]}$$

(We have no element of order $[n + 1]$ so we don't get a contribution by the ι_{X_M})

Lemma:

X_M rotates around $p \in M_0(X)$. We can find local coordinates x_i such that:

$$X_M = \lambda_1(x_2\partial_1 - x_1\partial_2) + \dots$$

And we define a 1 form θ^p via:

$$\theta^p = \lambda_1^{-1}(x_2dx_1 - x_1dx_2) + \dots$$

Properties:

- ⊗ $\mathcal{L}_{X_M}\theta^p = 0$
- ⊗ $\theta^p(X_M) = \Sigma x_i^2 = \|x\|^2$ (In the local trivial metric given by the coordinates)
- ⊗ We can find a θ as above such that near p : $\theta = \theta^p$

Let B_ϵ^p be the ϵ ball around the $p \in M_0(X)$

$$\begin{aligned} \int_M \alpha(X) &= \lim_{\epsilon \rightarrow 0} \int_{M - \cup B_\epsilon^p} \alpha(X) = \lim_{\epsilon \rightarrow 0} \int_{M - \cup B_\epsilon^p} d\left(\frac{\theta \wedge \alpha(X)}{D\theta}\right) \\ &= - \sum_p \lim_{\epsilon \rightarrow 0} \int_{S_\epsilon^p} \frac{\theta \wedge \alpha(X)}{D\theta} \end{aligned}$$

Rescaling: $x \mapsto \epsilon x$

- ⊗ ϵ -sphere S_ϵ becomes the unit sphere S_1
- ⊗ $\frac{\theta}{D\theta}$ remains unchanged
- ⊗ $\lim_{\epsilon \rightarrow 0} \alpha_\epsilon(X) = \alpha_{[0]}(X)(p)$

$$\int_{S_\epsilon^p} \frac{\theta \wedge \alpha(X)}{D\theta} = \int_{S_1^p} \frac{\theta \wedge \alpha_\epsilon(X)}{D\theta} = \alpha_{[0]}(X)(p) \int_{S_1} \frac{\theta}{D\theta}$$

$$- \int_{S_1} \frac{\theta}{D\theta} = \int_{S_1} \frac{\theta}{1 - d\theta} = \int_{S_1} \theta d\theta^{l-1} = \int_{B_1} d\theta^l = RHS$$

And:

$$(d\theta)^l = (-2)^l l! (\lambda_1 \dots \lambda_l)^{-1} dx_1 \wedge \dots \wedge dx_n$$

$2l$ dimensional unit ball has volume $\frac{\pi^l}{l!}$

Define the **equivariant Euler class** (for points!):

$$e_F(X)(p) = \lambda_1 \dots \lambda_l$$

\Rightarrow

$$RHS = \frac{(-2\pi)^l}{e_F(X)(p)}$$

QED

Remark:

⊗ There is also a more general formula for the case in which $M_0(X)$ is a submanifold N and not just a set of isolated points

⊗ We obtain it in a similar process by integration over $\{M - \text{tubular neighbourhood of } N\}$ and manipulating the integral.

$$\int_M \alpha(X) = \int_N \frac{\alpha(X)}{e_F(X)}$$

Where $e_F(X)$ is the **equivariant Euler form** of the **normal bundle** of N in M . (In our case it was the $e_F(X)(p = \lambda_1 \dots \lambda_l)$)

Let (M, ω) be a symplectic manifold of dimension $2l$.

$(\omega \in \Omega^2(M); \quad d\omega = 0$ and ω is invertible)

Let G be a symplectomorphic action ($g^*\omega = \omega$) on M .

A **moment map** is a function $\mu : \mathfrak{g} \times M \mapsto \mathbb{R}$ such that:

- ⊗ $\mu(X)$ is linear in $X \in \mathfrak{g}$
- ⊗ X_M is the **Hamiltonian** vector field generated by $\mu(X)$

$$d\mu(X)(\cdot) = \omega(X_M, \cdot)$$

- ⊗ $\mu(X)$ is equivariant: $g^*\mu(X) = \mu(Ad_g(X)) \quad \forall g \in G$

Let's add μ and ω :

$$X \mapsto \Omega(X) = \mu(X) - \omega$$

is an equivariant closed differential form.

$$D\Omega(X_M) = d\mu(X) - \omega(X_M, \cdot) = 0$$

We had a nice formula for integrals over equivariantly closed differential forms!

$\Omega(X)$ has maximally degree 2 so we integrate over:

$$e^{i\Omega}_{[n]} = e^{i\mu(X) + i\omega}_{[n]} = e^{i\mu(X)} e^{i\omega}_{[n]} = e^{i\mu(X)} \frac{\omega^l i^l}{l!}$$

Is also equivariantly closed.

Atiyah Bott \Rightarrow **The Duistermaat Heckmann localization**

$$\int_M e^{i\mu(X)} \frac{\omega^l}{l!} = (2\pi i)^l \sum_{p \in M_0(X)} \frac{e^{i\mu(X)}(p)}{e_F(X)(p)}$$

Example: S^2 with S^1 rotation around z localizes to a sum over the poles.

This is the so called **exact stationary phase approximation**.

We can use Duistermaat Heckman to proof that the stationary phase approximation of **certain** path integrals is exact!

Atiyah Bott localizations in susy language:

We saw in the last talk that integration of a differential form over a (bosonic) manifold is a special case of supergeometric integration:

$$\begin{aligned}
 (x^i, dx^i) &\rightarrow (x^i, \psi^i) \\
 \int_M dx^{i_1} \wedge \dots \wedge dx^{i_n} \alpha_{i_1 \dots i_n} &= \int_{\Pi T M} dx^1 \dots dx^n d\psi^1 \dots d\psi^n \alpha(x, \psi) \\
 &= (-2\pi)^l \sum_{p \in M_0(X)} \frac{\alpha(X)_{[0]}(p)}{e_F(X)(p)}
 \end{aligned}$$

$$\int_M dx^{i_1} \wedge \dots \wedge dx^{i_n} \alpha_{i_1 \dots i_n} = \int_{\Pi T M} dx^1 \dots dx^n d\psi^1 \dots d\psi^n \alpha(x, \psi)$$

$$D = d + \iota_{X_M} = \psi^i \frac{\partial}{\partial x^i} + X_M^i(p) \frac{\partial}{\partial \psi^i}$$

$$D^2 = \mathcal{L}_{X_M}$$

- ⊗ $\alpha(x, \psi)$ is a superfunction
- ⊗ D is a fermionic vectorfield
- ⊗ $D^2 = \mathcal{L}_{X_M}$ is a bosonic vectorfield

$D\alpha = 0$ is one of the conditions of the supersymmetric localization from the beginning of the talk.

Is the Atiyah Bott localization formula a special case of the supersymmetric localization formula?

We have to check whether we can write:

$$D = d + \iota_{X_M} = \psi^i \frac{\partial}{\partial x^i} + X_M^i(p) \frac{\partial}{\partial \psi^i}$$

as:

$$D = \frac{\partial}{\partial \psi^{i1}}$$

Is this possible?

Problem: That's not possible!

Theorem:

Let Q be a fermionic vectorfield on a supermanifold M that does not vanish at x_0 . Then we can write Q in local coordinates (x^i, ψ^j) around x_0 as:

$$\otimes Q = \frac{\partial}{\partial \psi^1} \Leftrightarrow Q^2 = 0$$

The proof can be found in [1], chapter 4 §4 section 2.

But: $D^2 = \mathcal{L}_{X_M} \neq 0$

\Rightarrow Atiyah Bott is **not** a special case of the susy localization from the beginning of the talk!

We now have susy localizations with fermionic vectorfields Q of the form ∂_{ψ^1} and $D = \psi^i \partial_{x^i} + X_M^i \partial_{\psi^i}$.

\Rightarrow There could be a more general localization formula for fermionic vectorfields!

To formulate the localization theorem for supermanifolds we have to define more structures on them.

Reminder: Facts about supermanifolds:

⊗ A *real* supermanifold $M = M^{(n_+|n_-)}$ can be seen as a outer product bundle $\Pi\alpha(N)$ over some bosonic manifold N .

⊗ $N = m(M)$ is called the **body** of M

⊗ We can find local coordinates $(x_1, \dots, x_{n_+}, \psi_1, \dots, \psi_{n_-})$

⊗ A **bosonic** vector field A on M has a **number part** $m(A)$

$$A = A^i(x, \psi)\partial_{x^i} + A^\nu(x, \psi)\partial_{\psi^\nu} \Rightarrow m(A) = A^i(x, 0)\partial_{x^i}$$

⊗ The **number part of an fermionic vector field** Q is a section in the bundle determined by $(q^1(x, 0), \dots, q^{n-}(x, 0))$.

$$Q = \kappa^i(x, \psi)\partial_{x^i} + q^l(x, \psi)\partial_{\psi^l}$$

⊗ Diffeomorphisms on M are automorphisms on $\alpha(N)$

⊗ Bosonic vectorfields A on M are infinitesimal diffeomorphisms on $M \iff$ infinitesimal automorphisms \bar{A} on αN

⊗ A bosonic vectorfield is **compact**, if it is generated by the action of a 1 parameter subgroup of a **compact** Lie group.

⊗ The set of compact vector fields on M is denoted by $\mathcal{K}(M)$

Superdivergence:

⊗ The *bosonic* divergence $\text{div}(X)$ of a *bosonic* vectorfield X on a *bosonic* manifold M tells us how the volume form dV on the manifold changes with the flow of X .

⊗ That's hard to define for supermanifolds!

⊗ Lets just define the **super divergence** div_{dV} by its action under superintegration:

$$\int_M dV Q(f) = - \int_M dV \text{div}_{dV}(Q) f \quad \forall f$$

Where M is a supermanifold, dV is a supervolume form on M , Q is a fermionic vectorfield and f a test function.

Supersymmetric localization Theorem:

Let M be a *compact supermanifold* with volumeform dV . Let Q be a fermionic vectorfield on M such that:

$$\operatorname{div}_{dV} Q = 0$$

$$Q^2 \in \mathcal{K}(M)$$

For any neighbourhood U of $M_0(Q)$ exists an bosonic, Q invariant function g_0 , that is equal to 1 in a neighbourhood $O \subset U$ of $M_0(Q)$ and vanishes outside. For every function h with $Q(h) = 0$ on M and every g_0 that satisfies this condition we have:

$$\int_M dV h = \int_M dV g_0 \cdot h$$

∂_{ψ^1} **Localization:**

$$\otimes \partial_{\psi^1}^2 \in \mathcal{K}(M)$$

$$\left(\frac{\partial}{\partial \psi^1} \right)^2 = 0 \in \mathcal{K}(M)$$

$$\otimes \operatorname{div}_{dV}(\partial_{\psi^1}) = 0$$

$$\int d\psi^1 \dots d\psi^{n-1} \operatorname{div}_{dV} \left(\frac{\partial}{\partial \psi^1} \right) \phi =$$

$$- \int d\psi^1 \dots d\psi^{n-1} \frac{\partial}{\partial \psi^1} \phi = - \int d\psi^2 \dots d\psi^{n-1} \left(\frac{\partial}{\partial \psi^1} \right)^2 \phi = 0$$

For every function ϕ .

Atiyah Bott Localization:

$$\otimes \quad \text{div}_{dV}(D) = 0$$

$$\begin{aligned} \int_M dV \text{div}_{dV}(D)\phi &= - \int_M dV D(\phi) \\ &= - \int_{m(M)} d\phi + \iota_X(\phi) = 0 \end{aligned}$$

due to stokes and the nonexistence of a $n + 1$ form on $m(M)$

$$\otimes \quad D^2 = \mathcal{L}_X \in \mathcal{K}(\Pi TM)$$

Because X is generated by the action of a 1 parameter subgroup of a compact Lie group and so is \mathcal{L}_X .

PROOF OF THE THEOREM

Lemma 1:

\exists a fermionic, Q^2 invariant function σ on M such that:

$$m(Q\sigma)(x) \neq 0 \quad \forall x \notin M_0(Q)$$

Proof:

\otimes Local coordinates: $z = (x^i, \psi^\alpha)$

$$Q = \sum_{i=1}^{n_+} a_\alpha^i(z) \psi^\alpha \frac{\partial}{\partial x^i} + \sum_{\alpha=1}^{n_-} b^\alpha(z) \frac{\partial}{\partial \psi^\alpha}$$

Where: $a_\alpha^i(z) = a_\alpha^i(x) + \dots$ and $b^\alpha(z) = b^\alpha(x) + \dots$

Where the dots denote higher orders in ψ^α

⊗ We can write in a similar manner:

$$Q^2 = k^i(z) \frac{\partial}{\partial x^i} + l_\beta^\alpha \psi^\beta \frac{\partial}{\partial \psi^\alpha}$$

With some coefficients $k^i(z) = k^i(x) + \dots$ and $l_\beta^\alpha(z) = l_\beta^\alpha(x) + \dots$ depending on a_α^i and b^α

⊗ $[Q, Q^2] = 0 \Rightarrow$

$$k^i(x) \frac{\partial b^\alpha(x)}{\partial x^i} - l_\beta^\alpha(x) b^\beta(x) = 0$$

The section in α generated by the number part $\overline{b^\alpha(x)}$ of Q is therefore invariant under the infinitesimal automorphism $\overline{Q^2}$

⊗ We assumed that $\overline{Q^2}$ is generated by a 1 parameter subgroup of a compact group G .

⊗ We can find a G invariant metric $g_{\alpha\beta}$ on the fibers of the bundle α because G is **compact**.

⊗ Define:

$$\sigma(z) = g_{\alpha\beta}(x)b^\alpha(x)\psi^\beta$$

⊗ $b^\alpha(x)$ and $g_{\alpha\beta}$ are $\overline{Q^2}$ invariant $\Rightarrow Q^2\sigma = 0$

⊗ $m(Q\sigma)(x) = g_{\alpha\beta}(x)b^\alpha(x)b^\beta(x) \neq 0 \quad \forall x \notin M_0(Q)$

That completes the proof of the Lemma 1.

⊗ Lets define:

$$\beta(z) = \frac{\sigma(z)}{Q\sigma(z)} \quad \forall z \notin M_0(Q)$$

⊗ $Q\beta = 1$ (Does this look familiar? Compare to $\frac{\theta}{D\theta}$)

Lemma 2:

We can find a partition of unity $\sum g_i = 1$ such that:

$$\text{supp}(g_0) \subset U$$

$$g_0|_O = 1$$

$$Qg_n = 0 \text{ and } g_n = Q(\rho_n) \text{ if } n \neq 0$$

Where $O \subset U$ are the neighbourhoods of $M_0(Q)$ from the Theorem.

Proof:

⊗ Choose an open covering (U_n) such that:

$$M_0(Q) \subset U_0 \text{ and } M_0(Q) \cap U_n = \emptyset \quad \forall n > 0$$

⊗ Choose a partition of unity f_n on this set.

⊗ The partition f_n is G -invariant. (We can always choose this because G is **compact**). It is also $\overline{Q^2}$ invariant.

⊗ Define:

$$g_n = Q(\beta f_n) \quad \forall n > 0$$

$$g_0 = 1 - \sum_{n>0} g_n$$

$$g_n = Q(\beta f_n) \quad \forall n > 0$$

$$g_0 = 1 - \sum_{n>0} g_n$$

Does this satisfy all conditions?

$$\sum_{n>0} g_n = \sum_{n>0} Q(\beta f_n) = \sum_{n>0} f_n + \beta Q\left(\sum_{n>0} f_n\right)$$

That's 0 in a neighbourhood of $M_0(Q)$ and 1 in $M - U_0$

Further: $Q(g_n) = Q(Q(\beta f_n)) = 0$ since $Q^2(f_n) = 0$

Proof of the Theorem:

Let h be a function that is invariant under Q .

$$\begin{aligned}\int_M dV h &= \sum_n \int_M dV g_n h = \sum_{n>0} \int_M dV Q(\rho_n) h + \int_M dV g_0 h \\ &= \sum_{n>0} \int_M dV Q(\rho_n h) + \int_M dV g_0 h = \int_M dV g_0 h\end{aligned}$$

Because $\text{div}_{dV}(Q) = 0$

Is this independent from the choice of g_0 ?

⊗ Assume that we have another function \tilde{g}_0 with the same properties as g_0

$$g_0 - \tilde{g}_0 = 0 \text{ in a small nbhd of } M_0(Q)$$

$$\Rightarrow (g_0 - \tilde{g}_0) = Q(\beta(g_0 - \tilde{g}_0))$$

$$\begin{aligned} \Rightarrow \int_M dV g_0 h - \int_M dV \tilde{g}_0 h &= \int_M dV Q(\beta(g_0 - \tilde{g}_0)) h = \int_M dV Q(\beta h (g_0 - \tilde{g}_0)) \\ &= 0 \end{aligned}$$







That completes the proof of the supersymmetric localization theorem.





A more general result can be found in [5]

- ⊗ Witten's proof of the Morse inequalities [6]
- ⊗ Calculation of **some** QFT partition functions and even some correlation functions [4]

SUMMARY:

- ⊗ The Atiyah Bott theorem can be proven with the means of equivariant differential forms.
- ⊗ The Duistermaat Heckman theorem is a corollary of the Atiyah Bott theorem. It provides the exactness of the stationary phase approximations in some cases.
- ⊗ The Atiyah Bott theorem can be rephrased as a localization theorem on certain supermanifolds.
- ⊗ The Atiyah Bott is a special case of a localization theorem on general supermanifolds.
- ⊗ The proof of the general theorem shows astonishing parallels to the proof of Atiyah Bott.

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