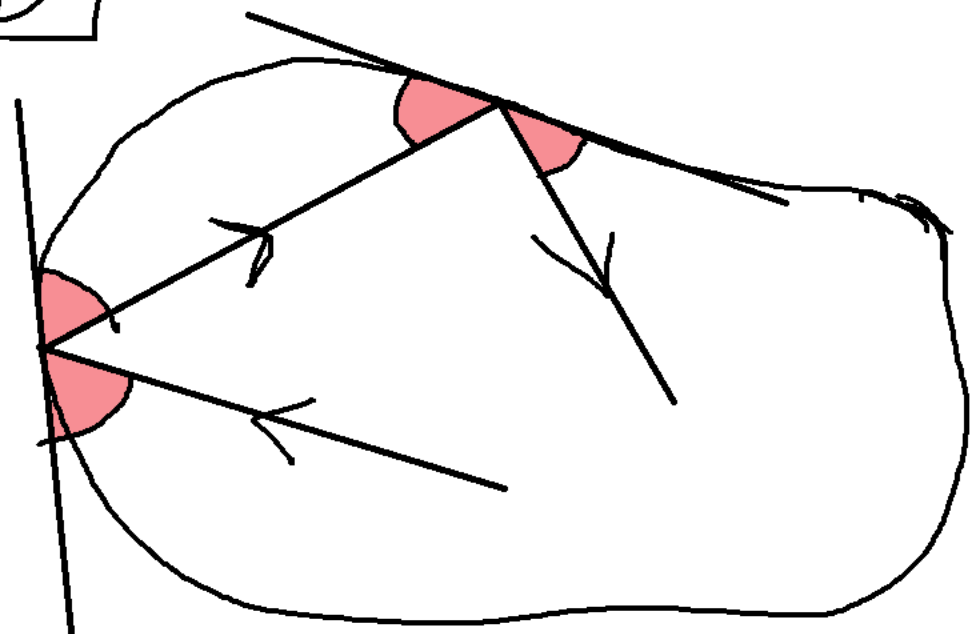


Magnetic billiards
&
Symplectic quotients

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2D



"normal" billiards
 "straight line flow" (SLF)



"magnetic" billiards
 "circular flow" (CF)
 constant radius R

SLF is "limit case $B=0$ "
 $R \rightarrow \infty$.

$R = \frac{1}{|B|}$, $B > 0$: counter-clockwise.
 $B \neq 0$ $B < 0$: clockwise.

(Work in progress)

2 Models: 1. Birkhoff billiards

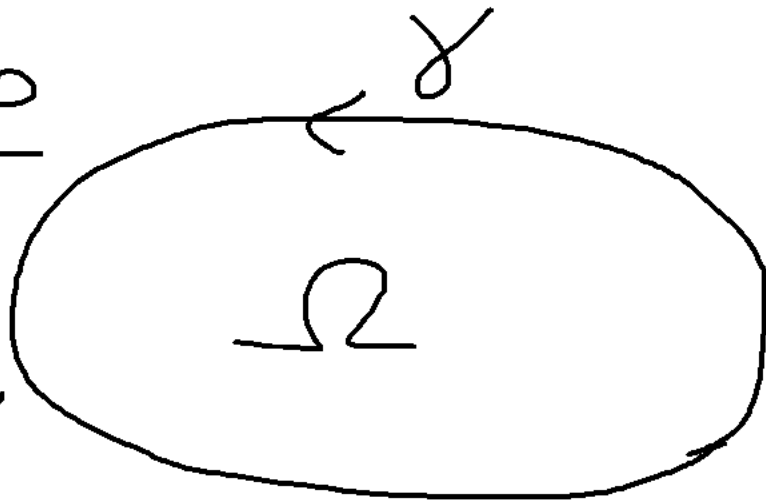
2. Orbit dynamics
(using symplectic quotients)

In both: Billiard flow as a discrete dynamics

$T: PS \rightarrow PS$, T is a symplectomorphism.
billiard map. \uparrow phase space

1. Birkhoff billiards: Setup

$\gamma: \mathbb{R}/\mathbb{Z} \rightarrow \mathbb{R}^2$ counter-clockw.
orientation,
smooth, $\|\gamma'\| \equiv 1$.



Regularity condition

SLF: Ω convex

CF:

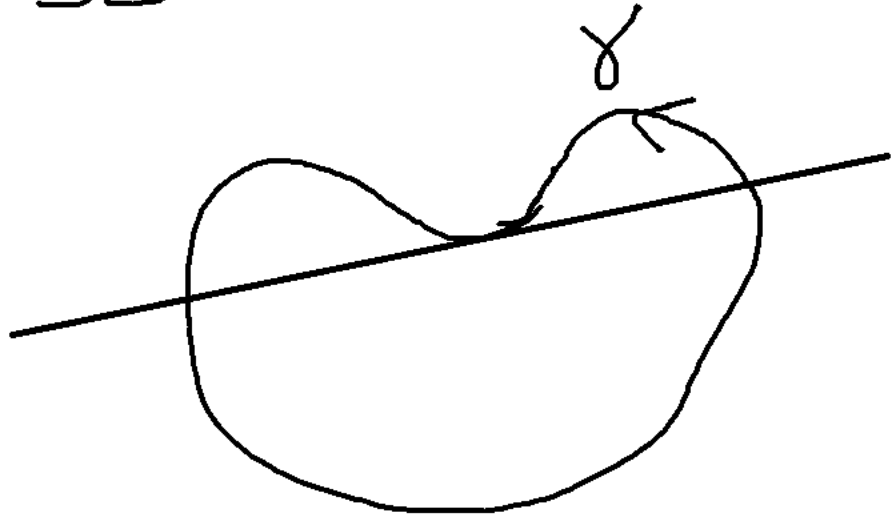
$R > \max_{\ell \in \mathbb{R}/\mathbb{Z}} \rho(\ell)$ or $R < \min_{\ell \in \mathbb{R}/\mathbb{Z}} \rho(\ell)$.

$\rho(\ell) := \frac{1}{\|\gamma''(\ell)\|}$, radius of curvature.

1. Birkhoff billiards: Setup

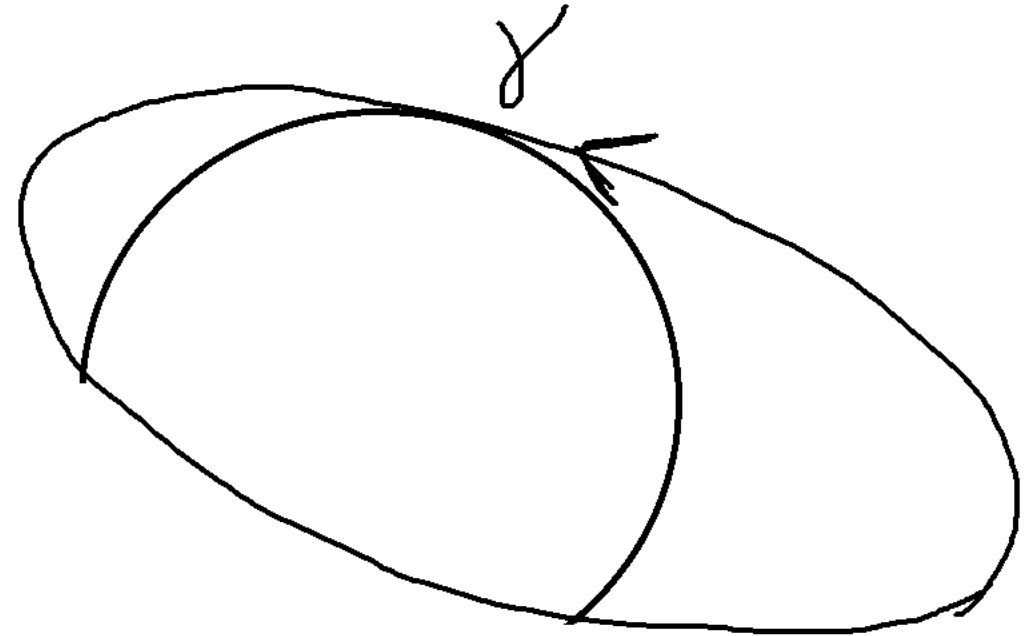
Regularity condition

SLF:



avoids "degenerate" cases:

CF:



1. Birkhoff billiards: Phase space.

$$\text{PS}_{\text{Birk}} = \mathbb{R}/\mathbb{L}\mathbb{Z} \times (0; \pi)$$

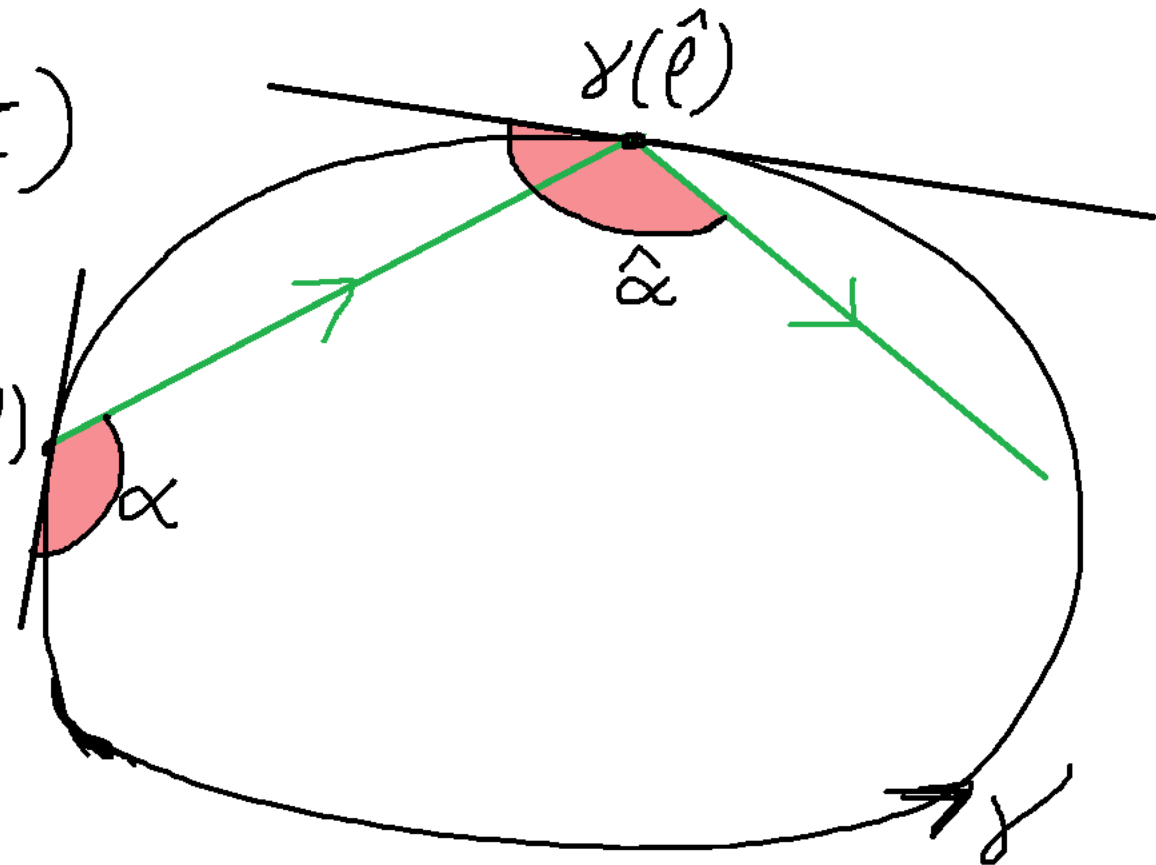
Coordinates (l, α)

l : Position on table boundary

$\gamma(l)$

α : Angle at which trajectory leaves boundary
(between traj. & $\gamma'(l)$)

$$T: (l, \alpha) \mapsto (\hat{l}(l, \alpha), \hat{\alpha}(l, \alpha)).$$



1. Birkhoff billiard: The billiard map.

$$T_B: (l, \alpha) \mapsto (\hat{l}(l, \alpha), \hat{\alpha}(l, \alpha)).$$

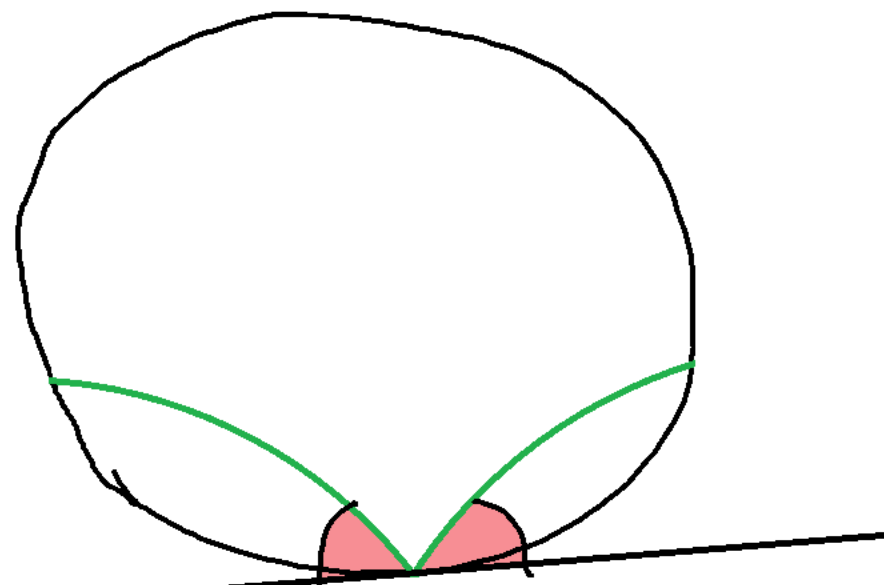
$$PS_{\text{Birk}} \longrightarrow PS_{\text{Birk}}.$$

Inverse map:

$$\text{Let } (\tilde{l}, \tilde{\alpha}) := T_{-B}(l, \pi - \alpha).$$

$$\text{Then } T_B^{-1}(l, \alpha) = (\tilde{l}, \pi - \tilde{\alpha}).$$

T_B is a diffeomorphism



1. Birkhoff billiards: Generating functions.

Proposition Consider a smooth map $T : \text{PS}_{\text{Birk}} \rightarrow \text{PS}_{\text{Birk}}$ and define

$\Delta := \{(l, l) \mid l \in \mathbb{R}/L\mathbb{Z}\} \subseteq \mathbb{R}/L\mathbb{Z} \times \mathbb{R}/L\mathbb{Z}$, the "diagonal". Let $G : (\mathbb{R}/L\mathbb{Z} \times \mathbb{R}/L\mathbb{Z}) \setminus \Delta \rightarrow \mathbb{R}$

be such that for $l_0, l_1, l_2 \in \mathbb{R}/L\mathbb{Z}$ and $\alpha_0, \alpha_1, \alpha_2 \in (0; \pi)$ following implication holds:

$$(l_0, \alpha_0) \xrightarrow{T} (l_1, \alpha_1) \xrightarrow{T} (l_2, \alpha_2) \implies \left. \frac{d}{dl} \right|_{l=l_1} [G(l_0, l) + G(l, l_2)] = 0. \quad (1)$$

Then the 2-form $\omega := \frac{\partial}{\partial \alpha} \left(\partial_1 G(l, \hat{l}(l, \alpha)) \right) d\alpha \wedge dl$ on PS_{Birk} is preserved by T .

Consider $F : \text{PS}_{\text{Birk}} \rightarrow \mathbb{R}$, $(l, \alpha) \mapsto G(l, \hat{l}(l, \alpha))$. If

$dF = \underbrace{-\cos \alpha}_{\text{circled}} dl + \underbrace{\cos \hat{\alpha}}_{\text{circled}} d\hat{l}$, then it works.

$$= \partial_1 G(l, \hat{l}(l, \alpha))$$

$$= \partial_2 G(l, \hat{l}(l, \alpha))$$

$$\omega = \sin \alpha d\alpha \wedge dl$$

1. Birkhoff billiards: Generating functions.

Generating function condition: $(l_0, \alpha_0) \xrightarrow{T} (l_1, \alpha_1) \xrightarrow{T} (l_2, \alpha_2) \implies \frac{d}{dl} \Big|_{l=l_1} [G(l_0, l) + G(l, l_2)] = 0.$

For $F : \text{PS}_{\text{Birk}} \rightarrow \mathbb{R}, (l, \alpha) \mapsto G(l, \hat{l}(l, \alpha))$, why is

$dF = -\cos \alpha dl + \cos \hat{\alpha} d\hat{l}$ enough?

Because this implies

$$\frac{d}{dl} \Big|_{l=l_1} (G(l_0, l) + G(l, l_2)) = \cos \alpha_1 - \cos \alpha_1 = 0.$$

Proof in this case that $\omega := \sin \alpha d\alpha \wedge dl$ is preserved:

$$0 = d^2 F = \sin \alpha d\alpha \wedge dl - \sin \hat{\alpha} d\hat{\alpha} \wedge d\hat{l} = \omega - T^* \omega. \quad \square$$

1. Birkhoff billiards: Generating functions.

Subtlety:
$$dF = \underbrace{-\cos \alpha}_{\partial_1 G} dl + \cos \hat{\alpha} d\hat{l}$$
$$= \partial_1 G(l, \hat{l}(l, \alpha))$$

So "cos α " is described depending on l, \hat{l} .

▽ Important for later. ▽

1. Birkhoff billiards: generating functions

Case $B=0$: $G: (l_1, l_2) \mapsto \|\gamma(l_1) - \gamma(l_2)\|_2$.

Proof that if $(l_1, \alpha_1) \xrightarrow{T} (l_2, \alpha_2)$, then $\partial_1 G = -\cos \alpha_1$
 $\partial_2 G = \cos \alpha_2$:

$$\partial_1 G = \langle \underbrace{\partial_{\gamma(l_1)} \|\gamma(l_1) - \gamma(l_2)\|_2}_{\text{unit vector from } \gamma(l_2) \text{ to } \gamma(l_1)}, \gamma'(l_1) \rangle$$

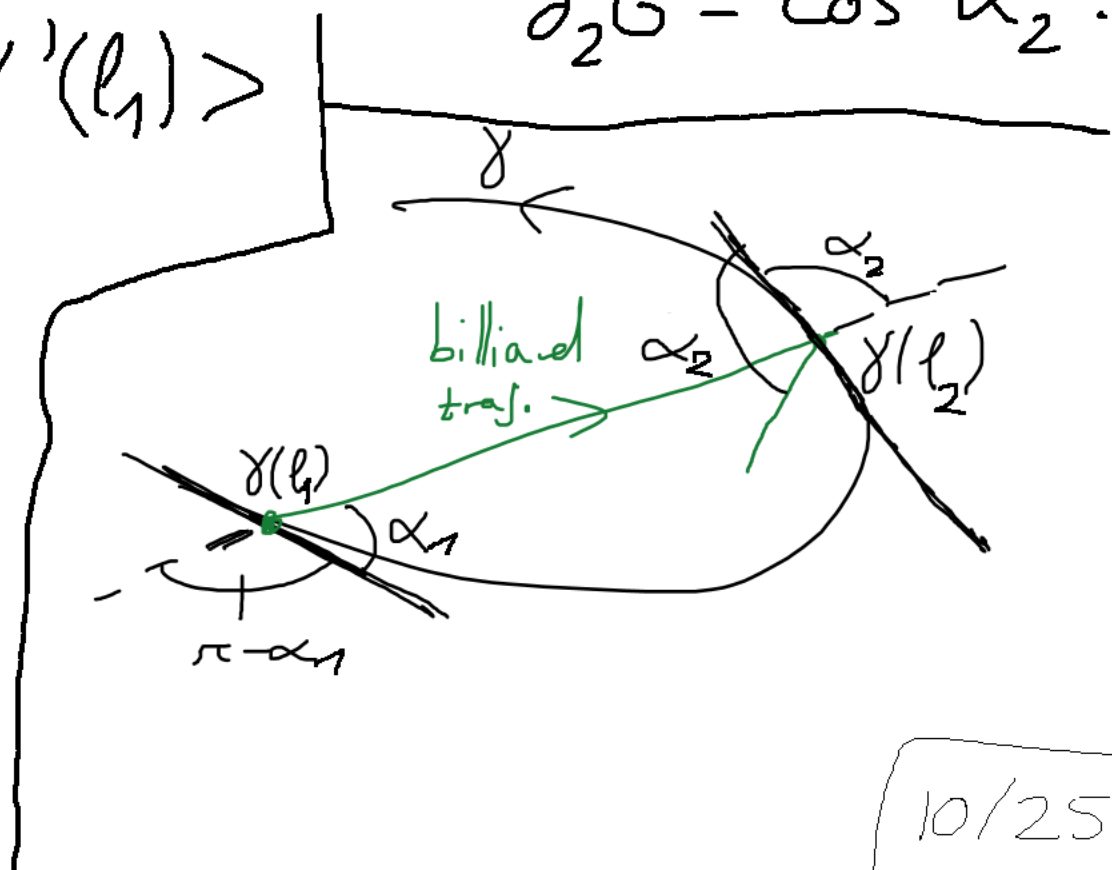
= unit vector from $\gamma(l_2)$ to $\gamma(l_1)$

$$= \cos(\pi - \alpha_1) = -\cos \alpha_1$$

$$\partial_2 G = \langle \underbrace{\partial_{\gamma(l_2)} \|\gamma(l_1) - \gamma(l_2)\|_2}_{\text{unit vector from } \gamma(l_1) \text{ to } \gamma(l_2)}, \gamma'(l_2) \rangle$$

= unit vector from $\gamma(l_1)$ to $\gamma(l_2)$

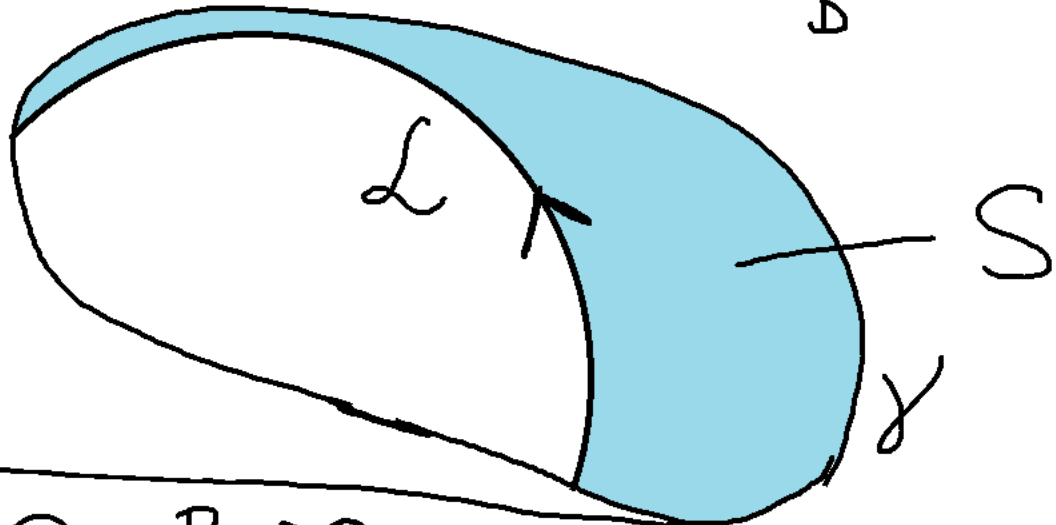
$$= \cos \alpha_2.$$



1. Birkhoff billiards : Generating functions

Case $B \neq 0$:

$$G_B = L + B \cdot S$$



L : Length of trajectory segment / circular arc

S : area to the right of trajectory, up to table boundary.

" $G_B \xrightarrow{B \rightarrow 0} G \text{ for } B=0$ "

[Source: J. Stat. Phys., 1996]

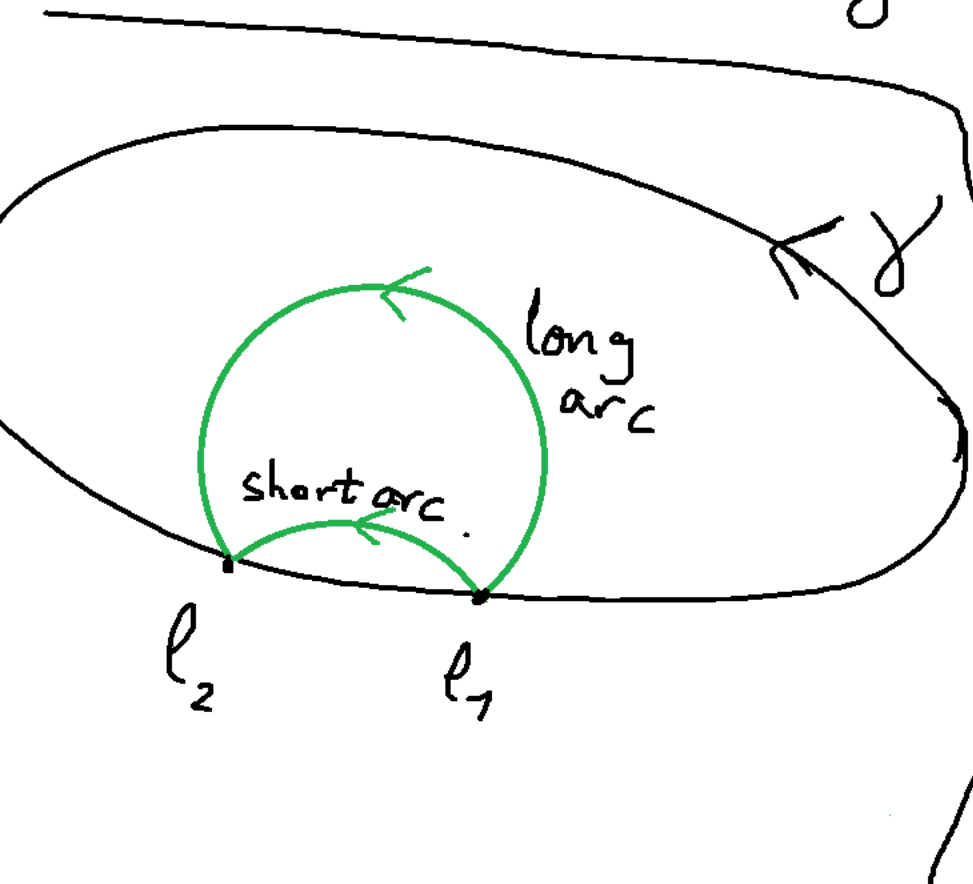
Source only considers $B > 0$, proof only for "small $B > 0$ "

1. Birkhoff billiards: generating functions

$B \neq 0$: For small R / big $|B|$,

$l_1, l_2 \rightsquigarrow$ maybe two possibilities.

Solution: two generating functions



G_B^+ : short arc, G_B^- : long arc

$$(l_1, \alpha_1^+) \xrightarrow{T_B} (l_2, \alpha_2^+),$$

$$(l_1, \alpha_1^-) \xrightarrow{T_B} (l_2, \alpha_2^-)$$

$$dG_B^\pm = -\cos \alpha_1^\pm dl_1 + \cos \alpha_2^\pm dl_2.$$

$\rightsquigarrow F: (l, \alpha) \mapsto G_B^\pm(l, \hat{l}(\alpha))$ ← choose depending on α

$$dF = -\cos \alpha dl + \cos \hat{\alpha} d\hat{l}$$

□

1. Birkhoff - Billiards: Summary:

$$PS_{\text{Birk}} = \mathbb{R}/\mathbb{Z} \times (0; \pi), \text{ Coord } (l, \alpha)$$

↑ position ↑ direction of velocity

$$T_{\mathbb{B}}: PS_{\text{Birk}} \rightarrow PS_{\text{Birk}} \text{ symplectomorphisms}$$

with $\omega = \sin \alpha \, d\alpha \wedge dl$, (proof by)

generating function $G_{\mathbb{B}}^{\pm}(l_1, l_2)$ with

$$F(l, \alpha) = G_{\mathbb{B}}^{\pm}(l, \hat{l}(l, \alpha)),$$

$$dF = -\cos \alpha \, dl + \cos \hat{\alpha} \, d\hat{l} \Rightarrow 0 = d^2 F = \omega - T_{\mathbb{B}}^* \omega.$$

2. Orbit dynamics

Step 1

Want to describe "straight line flow"

and

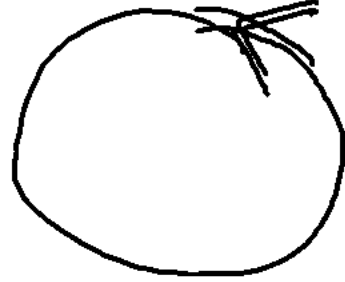
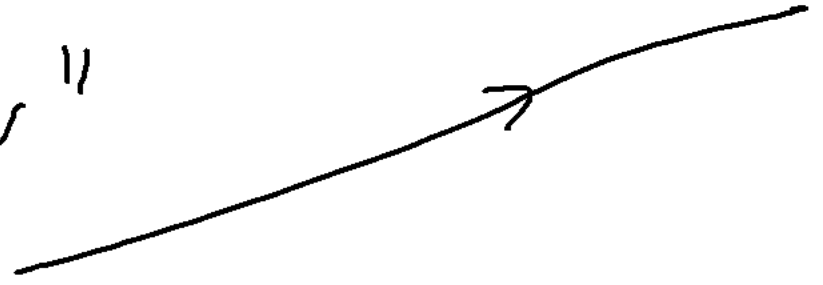
"circular flow"

as Hamiltonian flow on

$\mathbb{R}^N \times \mathbb{R}^N$ with coordinates (x, v)

Birkhoff: $N=2$.

Here, generalize construction to higher dimensions.



↑
position
of point
mass

↖
velocity
of point
mass.

Step 2 | Add the billiards.

2. Orbit dynamics: The physics.

$(\mathbb{R}^N \times \mathbb{R}^N, \omega)$ sympl. manifold.

$H: \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}$ Hamiltonian.

X_H Ham. vector field, uniquely given by $\omega(X_H, \cdot) = dH$

ϕ_t Ham. flow (of X_H).

If $\omega = \sum dx_i \wedge dp_i$, then

$$\omega(X_H, \cdot) = dH, \iff$$

$$\frac{\partial H}{\partial p_i} = \dot{x}_i$$

$$\frac{\partial H}{\partial x_i} = -\dot{p}_i$$

$$\frac{d}{dt} \phi_t = X_H \circ \phi_t$$

H : time-independent Hamiltonian.

p_i : generalized momenta.

2. Orbit dynamics of the physics.

$$\boxed{m=1}$$
$$\boxed{\text{charge} = -1}$$

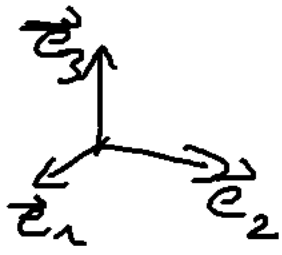
$N=2$ | $M = \mathbb{R}^2 \times \mathbb{R}^2$, coord. (x, p) , $\omega = dx_1 \wedge dp_1 + dx_2 \wedge dp_2$.

Straight line flow: No forces. $p_i = v_i$, $i=1, 2$.



$$H(x, p) = \frac{1}{2}|p|^2 = \frac{1}{2}|v|^2.$$

Circular flow: Lorentz force (Magnetic field $\vec{B} = B \cdot \vec{e}_3$)



$$p_1 = v_1 + \frac{B}{2}x_2 \quad \& \quad p_2 = v_2 - \frac{B}{2}x_1, \quad H(x, p) = \frac{1}{2} \left(\left(p_1 - \frac{B}{2}x_2 \right)^2 + \left(p_2 + \frac{B}{2}x_1 \right)^2 \right)$$

Change of coordinates (x, p) to (x, v) results in

$$H(x, v) = \frac{1}{2}|v|^2, \quad \omega = dx_1 \wedge dv_1 + dx_2 \wedge dv_2 + B dx_1 \wedge dx_2$$

\Rightarrow Hamiltonian is independent of B ,
 ω depends on B .

2. Orbit dynamics = Generalization to $N > 2$.

$M = \mathbb{R}^N \times \mathbb{R}^N$,
 coord. (x, v) , $H(x, v) = \frac{1}{2} \|v\|_2^2$,

SLF $\omega = \sum_{j=1}^N dx_j \wedge dv_j$, $X_H|_{(x,v)} = (v, 0)$, $\phi_t(x, v) = (x + tv, v)$.

CF $N = 2n$, $\omega = \sum_{j=1}^n dx_j \wedge dv_j + B \sum_{j=1}^n dx_j \wedge dx_{n+j}$,

with complex coord. $z_j = x_j + i x_{n+j}$, $w_j = v_j + i v_{n+j}$,

$X_H|_{(z,w)} = (w, B \cdot i w)$, $\phi_t(z, w) = (z + \frac{iw}{B} (1 - e^{iBt}), w e^{iBt})$

2nd component of flow is time-derivative of first component of flow: Because ω is of the form

$$\omega = \sum dx_j \wedge dv_j + \sum_{i,j} f_{ij} \cdot dx_i \wedge dx_j$$

2. Orbit dynamics

SLF: Flow induces \mathbb{R} -action on $M = \mathbb{R}^N \times \mathbb{R}^N$.

CF: Flow is $\frac{2\pi}{|\mathbf{B}|}$ -periodic (since $e^{i\mathbf{B}t}$ is $\frac{2\pi}{|\mathbf{B}|}$ periodic)

$\leadsto \mathbb{R}/P\mathbb{Z}$ -action, $P = \frac{2\pi}{|\mathbf{B}|}$.

Observe that $R = \frac{\|\mathbf{v}\|}{|\mathbf{B}|}$.

Restrict to $\|\mathbf{v}\|=1$: $Q := H^{-1}\left(\frac{1}{2}\right) = \{(x, v) \mid \|\mathbf{v}\|=1\}$.

$Q \subseteq M$ submanifold of codimension 1.

$\Rightarrow Q$ coisotropic, i.e. $T_q Q^\omega < T_q Q$

(Here $T_q Q^\omega = \{Y \in T_q M \mid \omega_q(Y, \tilde{Y}) = 0 \forall \tilde{Y} \in T_q Q\}$).

2. Orbit dynamics : Symplectic quotient.

(M, ω) sympl. manifold, $H: M \rightarrow \mathbb{R}$ Hamiltonian
with global ham. flow, inducing either

\mathbb{R} -action $\mathbb{R} \curvearrowright M$, $t \cdot m := \phi_t(m)$, or

$\mathbb{R}/P\mathbb{Z}$ -action $\mathbb{R}/P\mathbb{Z} \curvearrowright M$, $[t]m := \phi_t(m)$

\nearrow

Flow is periodic with period P everywhere.

Further assumptions :

- Action is free on $M \setminus \{\text{stationary points}\}$

- Fix $E \in \mathbb{R}$ regular value of H such that $Q := H^{-1}(E) \neq \emptyset$.

(It can be shown that the action restricts to Q .)

Action is proper on Q .

2. Orbit dynamics : symplectic quotient.

Then :

$$Q \subseteq (M, \omega)$$

$$\downarrow \pi$$

$$(\overline{Q} := Q/G, \overline{\omega})$$

π smooth surjective submersion,

$\overline{\omega}$ uniquely defined by

$$\pi^* \overline{\omega} = \omega|_Q, \quad \text{and}$$

$(\overline{Q}, \overline{\omega})$ is a symplectic manifold.

$$\dim \overline{Q} = \dim M - 2.$$

$G \curvearrowright M, \quad G = \mathbb{R} \text{ or } G = \mathbb{R}/\mathbb{Z}$
 $G \curvearrowright Q \subseteq M$
free, proper action on Q .
by Ham. flow.

"Quotient manifold theorem
+ Symplectic Structure"

$\overline{Q} = Q/G$ is the orbit space.

2. Orbit dynamics: Imagining the orbit space

$$\underline{N=2} \ (\|v\|=1) \quad Q = \mathbb{R}^2 \times S^1.$$

SLF $\overline{Q} = Q/\mathbb{R}$: Every line in \mathbb{R}^2 is a point in \overline{Q}
every orbit of the Hamiltonian flow.

CF $\overline{Q} = Q/(\mathbb{R}/P\mathbb{Z})$: Every circle of radius $\frac{1}{|B|}$
is a point in \overline{Q} .

Let $q \in Q$, then $\pi(q) = \cdot q$ is the orbit of q in Q .

$$T_{\overline{q}} \overline{Q} \cong \frac{T_q Q}{T_q Q^{\omega}} = \frac{T_q Q}{\text{span}\{X_{\#}|_q\}}, \quad d\pi|_q : T_q Q \longrightarrow \frac{T_q Q}{\text{span}\{X_{\#}|_q\}}$$

$Y \mapsto [Y]$.

2. Orbit dynamics: The billiard map

$N=2$

$$\Theta \subseteq \overline{Q} = Q/G$$

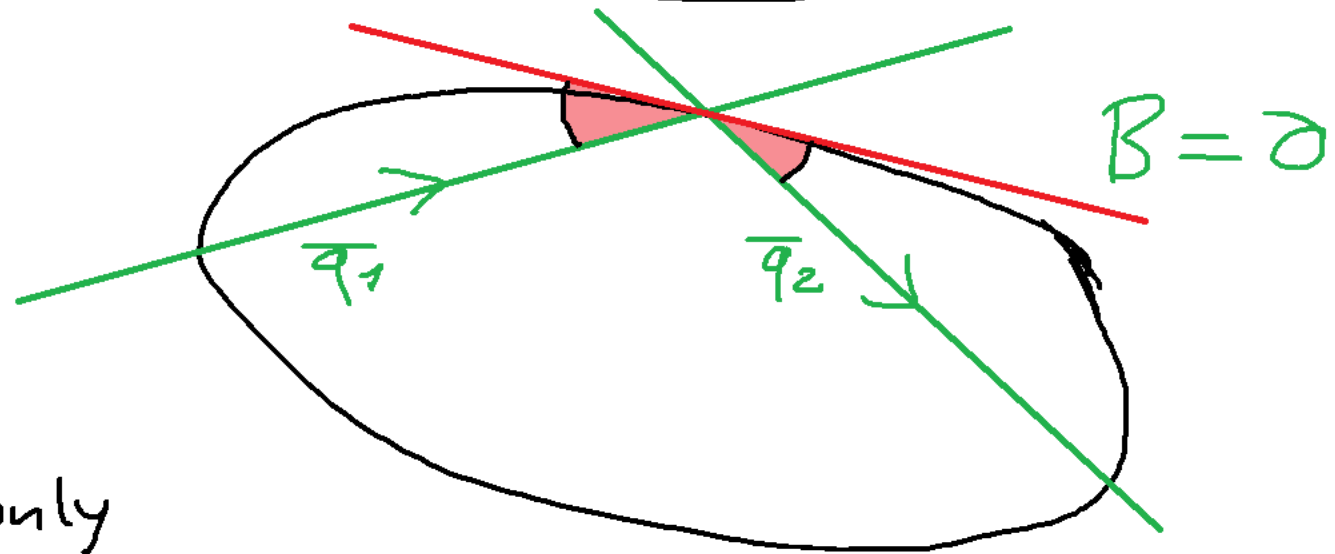
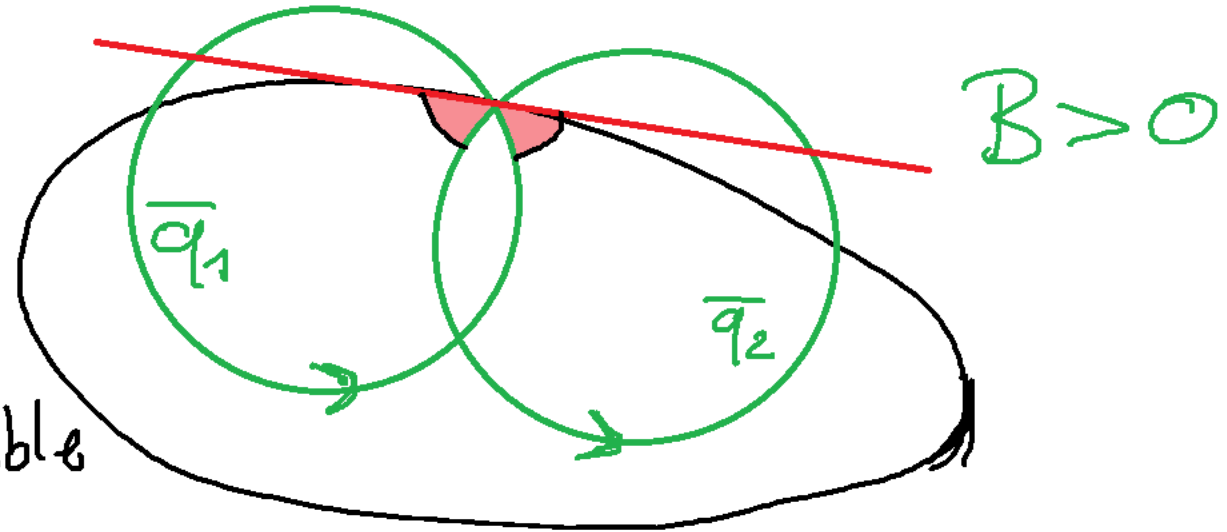
open subset of all orbits which transversally intersect billiard's table boundary.

$$T_B: \Theta \rightarrow \Theta.$$

Regularity conditions

$\Rightarrow T_B$ is well-defined.

(Every orbit intersects table in only one trajectory segment)



$$\overline{q_1} \xrightarrow{T} \overline{q_2}$$

2. Orbit dynamics: my results

▶ $T_B: \mathcal{O} \rightarrow \mathcal{O}$ is a symplectomorphism.

▶ For $N=2$, choosing the natural map

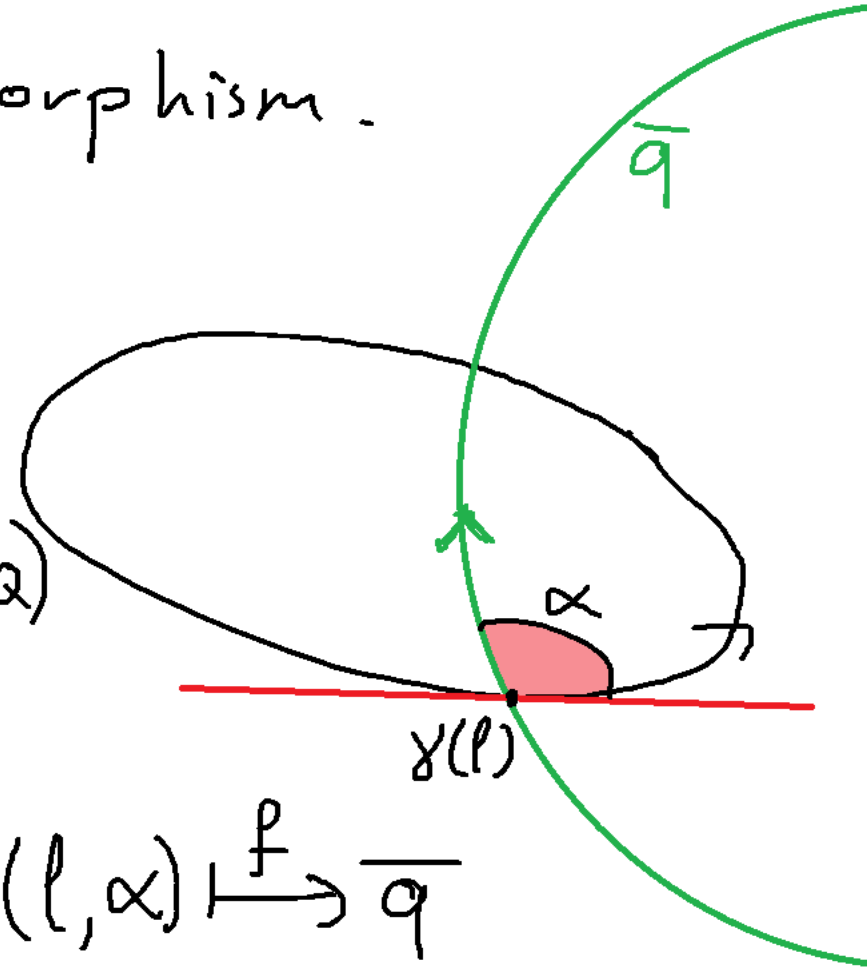
$f_B: PS_{Birk} \rightarrow \mathcal{O}$, and with

$\bar{\omega}$ given by sympl. Quotient ($\pi^* \bar{\omega} = \omega|_Q$)

and $\omega_{Birk} = \sin \alpha \, d\alpha \wedge dl$,

$$\boxed{f_B^* \bar{\omega} = \omega_{Birk}} \quad \begin{array}{l} \text{for } B \neq 0 \\ \text{and } B = 0 \end{array}$$

$$(l, \alpha) \xrightarrow{f} \bar{q}$$



2. Orbit dynamics: my results.

For SLF: $(\bar{Q}, \bar{\omega}) \cong (T\mathbb{S}^{N-1}, \omega_{std})$

(Pull back ω_{std} on $T^*\mathbb{S}^{N-1}$ via $T\mathbb{S}^{N-1} \rightarrow T^*\mathbb{S}^{N-1}$
 $(v, x) \mapsto (v, \langle x, \cdot \rangle)$.

$\langle \cdot, \cdot \rangle$ on $T_v\mathbb{S}^{N-1}$ given by
 $\mathbb{S}^{N-1} \subseteq \mathbb{R}^N$ submanifold structure)

$\bar{q} \in \bar{Q}$
 $v \parallel v \parallel = 1$.

$v \mapsto (v, x) \in T\mathbb{S}^{N-1}$
 x unique point on line \bar{q} such that

$\langle x, v \rangle = 0$.

$\Rightarrow x \in T_v\mathbb{S}^{N-1} \cong \{v\}^\perp$

2. Orbit dynamics: My results

For CF:

$$(\bar{Q}, \bar{\omega}) \cong (\mathbb{R}^{2n} \times \mathbb{C}P^{n-1}, B \cdot \omega_{\mathbb{R}^{2n}} - \frac{1}{B} \omega_{\mathbb{C}P^{n-1}})$$

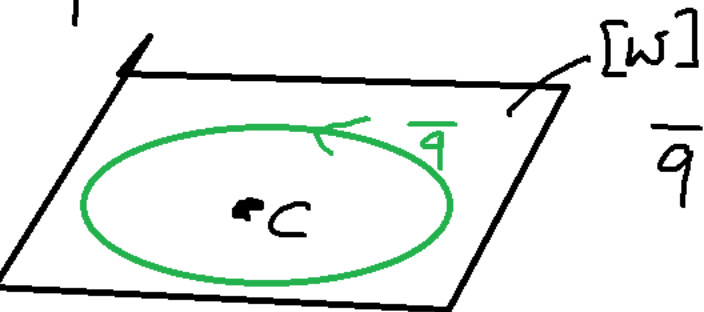
$\omega_{\mathbb{R}^{2n}} = dx \wedge dy = \sum_{i=1}^n dx_i \wedge dy_i$ standard sympl. form.

$\omega_{\mathbb{C}P^{n-1}}$ sympl. structure with $\mathbb{C}P^{n-1}$ as sympl. quotient:

$H: \mathbb{R}^{2n} \rightarrow \mathbb{R}, (x, y) \mapsto -\frac{1}{2} \|x, y\|^2$, Ham. flow induces $\mathbb{R}/2\pi\mathbb{Z}$ -action.

Action: $z_j = x_j + iy_j$ complex coord, $\phi_t(z) = e^{it} z$.

$$\mathbb{C}P^{n-1} = H^{-1}(-\frac{1}{2}) / (\mathbb{R}/2\pi\mathbb{Z}) = \mathbb{S}^{2n-1} / \mathbb{S}^1$$



$\bar{q} \mapsto (\mathbb{C}, [w])$

center of orbit circle

linear complex plane parallel to the affine plane in which orbit lies.

Thank you for your time! ▽